Calculations of the Black Hole Masses in IC 2560 and UGC 3193

Alina Kaliszewski 1,2 and Jim Braatz²

¹University of Minnesota Department of Physics and Astronomy 116 Church St SE Minneapolis, MN 55455, USA ²National Radio Astronomy Observatory 520 Edgemont Road Charlottesville, VA 22903, USA

ABSTRACT

Using circumnuclear water maser observations obtained from the Green Bank Telescope (GBT) and the Very Long Baseline Array (VLBA), we calculated the masses of the supermassive black holes (SMBHs) at the center of the active galactic nucleus (AGN) galaxies IC 2560 and UGC 3193. The SMBH mass for IC 2560, as measured by maser emission in Keplerian rotation around the black hole, was found to be $(5.3 \pm 0.2) \times 10^6 M_{\odot}$. We determined the upper limit on the SMBH mass for UGC 3193 to be $(0.6 \pm 0.02) \times 10^6 M_{\odot}$. The maser emission for UGC 3193 is likely occurring outside of the SMBH's gravitational sphere of influence, so our calculations reflect the enclosed mass. A preliminary geometric distance to IC 2560 was also calculated to be $39.3^{+1.2}_{-0.9}$ Mpc, which is consistent with other distances calculated using the 21cm velocity of 2923 ± 10 km s⁻¹ and the most recent value of the Hubble constant published by the Megamaser Cosmology Project, 73.9 ± 3.0 km s⁻¹ Mpc⁻¹.

1. INTRODUCTION

By observing water maser emission in active galactic nucleus galaxies (AGNs), it is possible to determine the masses of the supermassive black holes (SMBHs) at the centers of these galaxies, the distances to the galaxies, and orientation parameters associated with the maser disk. Water maser emission occurs at a frequency of 22 GHz, and can be observed with the Green Bank Telescope (GBT) and the Very Long Baseline Array (VLBA). Masers are dynamical tracers, which allow for very precise measurements of their positions and velocities.

Edge-on maser disks display triple peaked maser emission patterns. Triple peaked masers typically exhibit emission at the galaxy's systemic velocity, in addition to symmetrical redand blueshifted features centered around the systemic features. The systemic features arise on the near side of the edge-on disk. The redand blueshifted features arise on the tangential edges of the disk, rotating away from (redshifted) or toward (blueshifted) the observer. The positions and velocities of maser features, obtained through Very Long Baseline Interferometry (VLBI), can be used to determine the mass of the central black hole. When combined with these positions and velocities, the measured centripetal accelerations of individual maser components allow for determination of the distance to the galaxy.

Megamasers, emitted by Seyfert 2 or LINER active galactic nucleus galaxies (AGNs), display isotropic luminosities of approximately 6 orders of magnitude higher than average Galactic masers (Braatz & Gugliucci 2008). Circumnuclear H₂O megamasers typically form in disks less than 1 pc from their central black holes (Lo 2005). The megamaser disks which we can detect are edge-on to our line of sight, and the centripetal acceleration typically exhibits Keplerian rotation. Maser disks may occur at many different orientations, but an inclination angle away from our line of sight results in a shorter gain path and hence a smaller amplification factor. A maser disk which does not display Keplerian rotation is often an indication that there are additional gravitational forces acting on the disk.

SMBH masses in maser systems are typically on the scale of $10^6 M_{\odot}$ to $10^7 M_{\odot}$ (Pesce et al. 2020b; Braatz et al. 2010; Gao et al. 2017). Other black hole mass measurement techniques include the use of gravitational waves or mapping reverberations of AGN continuum emission (Yu & Chen 2021). The $M_{BH} - \sigma$ relation places typical black hole masses in the range of $10^5 M_{\odot}$ to $10^{10} M_{\odot}$ (Bennert et al. 2015; Zhou et al. 2021). Optical telescopes can be used to determine BH masses in elliptical galaxies (e.g. Rev et al. (2021), but dusty nuclei in spiral galaxies obscure less massive black holes. Radio emission is unaffected by this dust, so masers can be used to study these less massive black holes (Blain et al. 2004).

The Megamaser Cosmology Project is using masers to investigate the Hubble tension, as geometric distances to masers provide an independent alternative to the distance ladder constructed using Cepheid Variables. The maser technique requires high precision VLBI maps and acceleration data, and their methods are described in Reid et al. (2009).

Maser emission was first detected in IC 2560 in 1994 (Braatz et al. 1994) and in UGC 3193 in 2008 (Braatz & Gugliucci 2008). There is no maser emission observed at the systemic velocity of UGC 3193, despite symmetric red- and blueshifted emission (Braatz & Gugliucci 2008). IC 2560 does exhibit observable maser emission at its systemic velocity, which makes it a candidate for calculating its distance using masers, due to the nonzero accelerations of the systemic components. Jan Wagner (private communication) used VLBI imaging and GBT data to study the kinematics of both UGC 3193 and IC 2560 with a model fitting technique predating the MCP's current 3 dimensional Monte Carlo Markov Chain (MCMC) approach.

2. IMPROVED BLACK HOLE MASS ESTIMATES

Previous studies of maser emission have involved model fitting techniques such as those described in Reid et al. (2009), Braatz et al. (2010), and Yamauchi et al. (2012). We analyzed the kinematic data obtained from Wagner's observations using a 3 dimensional MCMC model written in Python by Dom Pesce (Pesce et al. 2020b). Pesce's 3 dimensional model received inputs such as the positions of the maser emission, obtained using VLBI data, the velocities of each maser point, obtained using spectral analysis, and line-of-sight accelerations for each maser component. We determined individual maser component accelerations by visually identifying peaks in galaxy emission spectra from approximately monthly GBT monitoring observations and fitting a straight line through the peaks from multiple epochs (see Figure 1).

The model fitted a 3 dimensional disk with warping considered in the directions of both the position and inclination angles (see Appendix B for an input control file). It output the results of the MCMC fitting as median values with confidence intervals for global parameters such as the black hole mass, position, and recession velocity, in addition to the distance to the galaxy and maser disk warping parameters (Pesce et al. 2020b).

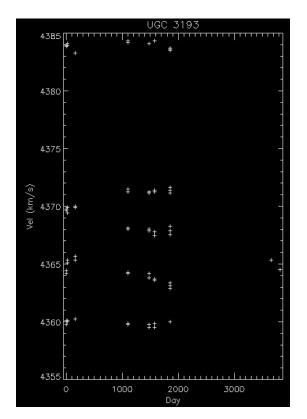


Figure 1. Velocity vs Time Plot for Acceleration Calculations

2.1. IC 2560

The VLBI map for IC 2560 (see Figure 2) was constructed using only data points with SNR values greater than 5 (see Appendix A). The orange data point at (-0.226, 1.345) was assigned to be the result of black hole outflow or other gas and dust unrelated to the maser disk. As a result, this point was not included in the disk model fitting. This map shows that the maser disk has a diameter of just below 1 pc, which is typical for edge-on maser disks.

We separated IC 2560's maser features into 4 different groups for model fitting in order to study the maser disk's behavior at different radii. The inner features, which do not include the systemic components, were located at radii less than 0.3 pc, and the outer features were located at radii greater than 0.3 pc. We also studied trials involving both the inner and outer components, and all maser emission (i.e., inner and outer plus systemic). These 4 trials are dis-

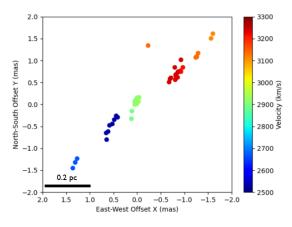


Figure 2. VLBI Map for IC 2560

played in Table 1. All trials were fit with a flat maser disk, due to the lack of visible warping in IC 2560's VLBI map.

For the first 3 trials, the distance to the galaxy was set to a fixed value of 39.6 ± 1.6 Mpc. This distance was calculated using the 21cm line velocity of 2923 ± 10 km s⁻¹ and the Hubble constant value of 73.9 ± 3.0 km s⁻¹ Mpc⁻¹ published by the Megamaser Cosmology Project in 2020 (Pesce et al. 2020a). When the accelerations from the systemic maser features were included in the final trial, the model fitted the geometric distance to the galaxy using a uniform prior. For all trials, the model fitted both the SMBH mass and the maser disk's position angle using a uniform prior.

2.2. UGC 3193

The VLBI map for UGC 3193 (see Figure 3) shows a maser disk diameter of 2-3 pc, which is more extended than typically expected for a maser of this type. Previous measurements of similar maser disks have resulted in sub-pc diameters ranging from 0.18 pc to 0.6 pc (Braatz & Gugliucci 2008; Braatz et al. 2010). Because UGC 3193 displays no detectable maser emission at its systemic velocity, we were unable to fit the distance to the galaxy. In order to determine a SMBH mass, we adopted a fixed distance of 60.3 ± 2.5 Mpc, calculated using the HI line velocity of 4454 ± 10 km s⁻¹ and the Megamaser

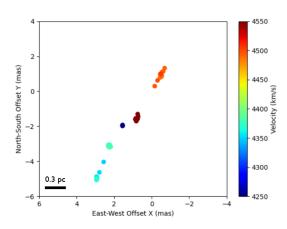


Figure 3. VLBI Map for UGC 3193

Cosmology Project's Hubble constant value of $73.9 \pm 3.0 \text{ km s}^{-1} \text{ Mpc}^{-1}$ (Pesce et al. 2020a). The radial structure of the maser shows a pronounced kink, which we attempted to fit using second order warping parameters. To explore the behavior of maser components at different radii, we ran several trials of the model fit. For some iterations, we limited the data to only the inner or outer maser features. We defined the inner maser components to be those at a radius less than 0.3 pc and the outer maser components to be those at a radius greater than 0.3 pc. The trials for each individual ring were run with the assumption of a flat maser disk. We also conducted a trial using both the inner and outer (i.e., all data points, see Appendix A) features. This trial made use of the model's 3D warp fitting capabilities to take into account the visible warp in the middle of the VLBI map. The SMBH mass and position angle of the maser disk were both calculated using uniform priors. These results are shown in Table 2.

3. RESULTS AND DISCUSSION 3.1. *IC 2560*

The SMBH mass values from different trial runs are within $1-2\sigma$ of each other, with the ex-

ception of the trial using only the outer maser components. There were only 9 maser components designated as outer features at a radius greater than 0.3 pc, and the uncertainties are higher in this trial than in others. The outlier points at (-0.226, 1.345) were omitted. The trial run on the outer maser components resulted in a mass of $(4.6^{+0.4}_{-0.3}) \times 10^6 M_{\odot}$, while the other trials ranged from $(5.3 \pm 0.2) \times 10^6 M_{\odot}$ to $(5.6 \pm 0.2) \times 10^6 M_{\odot}$. These masses are all in the lower end of the range of typical maser system SMBH masses. The geometric distance calculated by the model fit for IC 2560, $39.3^{+1.2}_{-0.9}$ Mpc, is within 1σ of the value of 39.6 ± 1.6 Mpc calculated using the 21cm velocity and H₀.

The position angle values range from $-45.9^{+1.2}_{-1.1}$ degrees to $-49.2^{+0.7}_{-0.7}$ degrees. The lower bound of this range is in agreement with Yamauchi et al. (2012), and the range is consistent with visual observations of the VLBI map.

3.2. UGC 3193

The central masses for UGC 3193 are not in agreement with each other, ranging from $(0.6\pm0.2)\times10^6 M_{\odot}$ to $(1.2\pm0.03)\times10^6 M_{\odot}$. The smallest value, which comes from the trial using only the inner maser components, is below the range of typical maser galaxy SMBH masses, but the trials run using the outer and all maser components result in mass values within the low end of the typical range for maser systems. Taking into consideration the large maser disk diameter and relatively low rotation velocities and mass values, it is likely that the maser emission is occurring outside of the gravitational sphere of influence of the black hole. This would indicate that we are seeing the enclosed mass as opposed to the black hole mass. This idea is also supported by the fact that the enclosed mass value increases as the radius of the fitted features increases.

The wide range of position angles, from -30.2 ± 0.2 degrees to -68.8 ± 2.0 degrees, is

Inner or	Distance	Distance	Mass	Ω_0
Outer	Prior	(Mpc)	$(10^7 M_{\odot})$	(degrees)
Ι	F	$39.6^{+1.6}_{-1.6}$	$0.56^{+0.02}_{-0.02}$	$-48.6^{+1.3}_{-1.4}$
Ο	F	$39.6^{+1.6}_{-1.6}$	$0.46\substack{+0.04\\-0.03}$	$-45.9^{+1.2}_{-1.1}$
I+O	\mathbf{F}	$39.6^{+1.6}_{-1.6}$	$0.56\substack{+0.02 \\ -0.01}$	$-47.5_{-0.9}^{+0.8}$
All	U	$39.3^{+1.2}_{-0.9}$	$0.53^{+0.02}_{-0.02}$	$-49.2^{+0.7}_{-0.7}$

Table 1. IC 2560

NOTE—Column 1 indicates which maser features were analyzed. Column 2 indicates whether the distance was set to a fixed value or fit to a uniform prior. Column 5 contains the position angle of the maser disk.

 Table 2. UGC 3193

Inner or	Distance	Distance	Mass	Ω_0
Outer	Prior	(Mpc)	$(10^7 M_{\odot})$	(degrees)
Ι	F	$60.3^{+2.5}_{-2.5}$	$0.06^{+0.02}_{-0.02}$	$-63.8^{+2.0}_{-2.0}$
Ο	\mathbf{F}	$60.3^{+2.5}_{-2.5}$	$0.10\substack{+0.01 \\ -0.01}$	$-30.2^{+0.2}_{-0.2}$
All	F	$60.3^{+2.5}_{-2.5}$	$0.12^{+0.003}_{-0.003}$	$-68.8^{+3.6}_{-3.7}$

NOTE—Column 1 indicates which maser features were analyzed. Column 2 indicates whether the distance was set to a fixed value or fit to a uniform prior. Column 5 contains the position angle of the maser disk.

due to the shape of the maser disk seen in UGC 3193's VLBI map. The warp visible in the inner maser features results in a much larger position angle than is seen when analyzing the outer data points. It is likely that the lack of observed systemic maser emission is a result of the disk warp or the maser disk being offset by some angle from our line of sight.

4. CONCLUSION

Using a 3 dimensional Monte Carlo Markov Chain model fit on maser emission data, we calculated the mass of the supermassive black hole at the center of the Seyfert 2 galaxy IC 2560 to be $(5.3 \pm 0.2) \times 10^6 M_{\odot}$. Following a similar method, we also calculated the enclosed mass in the region around the supermassive black hole at the center of UGC 3193 to have an upper limit of $(0.6 \pm 0.02) \times 10^6 M_{\odot}$. Preliminary calculations also resulted in a geometric distance to IC 2560 of $39.3^{+1.2}_{-0.9}$ Mpc, which supports the current value of H_0 from the Megamaser Cosmology Project. Further analysis of this galaxy is necessary to confirm this value.

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APPENDIX

A. MASER DATA

Table 3.Data for IC 2560							
Velocity (km/s)	X (mas)	Error in X	Y (mas)	Error in Y	SNR		
2522.99	0.416	0.050	-0.292	0.122	5.3		
2523.84	0.526	0.064	-0.437	0.178	5.3		
2524.70	0.452	0.038	-0.257	0.114	7.1		
2525.56	0.485	0.037	-0.345	0.108	6.4		
2528.13	0.585	0.039	-0.469	0.098	7.0		
2528.98	0.615	0.030	-0.611	0.086	7.8		
2529.84	0.651	0.044	-0.795	0.132	5.5		
2530.70	0.660	0.051	-0.642	0.133	5.4		
2665.40	1.365	0.061	-1.447	0.153	5.4		
2666.26	1.312	0.033	-1.314	0.095	8.9		
2671.41	1.277	0.058	-1.228	0.177	5.2		
2890.26	0.017	0.033	0.042	0.088	6.9		
2891.12	-0.020	0.040	0.104	0.121	6.3		
2891.98	0.012	0.029	0.020	0.091	7.9		
2892.84	0.127	0.030	-0.324	0.108	7.4		
2893.70	0.115	0.025	-0.147	0.071	9.0		
2894.56	0.051	0.018	0.071	0.055	10.7		
2895.42	0.029	0.016	0.123	0.048	12.8		
2986.28	0.027	0.015	0.073	0.041	15.6		
2897.14	0.036	0.013	0.054	0.036	17.9		
2897.99	0.034	0.013	0.063	0.035	18.3		
2898.85	0.027	0.014	0.107	0.038	17.1		
2899.71	0.045	0.012	0.063	0.035	18.2		
2900.57	0.038	0.011	0.050	0.030	21.1		
2901.43	0.032	0.010	0.064	0.028	23.7		
2902.29	0.032	0.008	0.071	0.023	28.0		
2903.15	0.027	0.009	0.106	0.024	26.2		
2904.01	0.028	0.009	0.125	0.025	25.1		
2904.87	0.039	0.009	0.084	0.025	25.2		
2905.73	0.029	0.011	0.103	0.030	21.7		

Table 3. Data for IC 2560

Velocity (km/s)	X (mas)	Error in X	Y (mas)	Error in Y	SNR
2906.58	0.025	0.010	0.110	0.026	24.1
2907.44	0.002	0.010	0.155	0.028	22.2
2908.30	-0.002	0.011	0.156	0.031	20.2
2909.16	0.018	0.012	0.091	0.032	19.5
2910.02	0.029	0.012	0.088	0.032	19.5
2910.88	0.030	0.012	0.103	0.033	19.3
2911.74	0.024	0.013	0.116	0.035	16.8
2912.60	0.005	0.010	0.139	0.030	20.6
2913.46	0.009	0.009	0.107	0.026	24.4
2914.32	0.017	0.012	0.099	0.031	21.1
2915.18	0.016	0.013	0.125	0.034	18.4
2916.04	0.036	0.018	0.053	0.051	13.0
2916.89	0.033	0.020	0.020	0.057	12.6
2917.75	0.032	0.025	0.056	0.070	9.5
2918.61	0.058	0.022	0.007	0.062	9.3
2919.47	0.042	0.019	0.047	0.053	10.9
2920.33	0.029	0.023	0.082	0.057	11.1
2921.19	0.022	0.034	0.038	0.088	7.2
2922.05	0.027	0.035	0.127	0.111	5.2
2922.91	-0.036	0.036	0.163	0.095	5.3
2928.06	-0.022	0.028	0.064	0.073	5.9
3114.42	-1.563	0.054	1.510	0.137	5.8
3115.28	-1.599	0.046	1.621	0.124	6.0
3135.04	-0.226	0.054	1.345	0.126	5.2
3136.76	-1.288	0.053	1.175	0.179	5.8
3136.79	-1.259	0.021	1.092	0.058	15.1
3137.62	-1.237	0.047	1.074	0.142	6.5
3137.65	-1.255	0.023	1.091	0.063	13.7
3216.80	-0.914	0.076	0.771	0.181	5.0
3217.66	-0.964	0.032	0.844	0.090	9.0
3218.52	-0.921	0.040	0.750	0.113	7.0
3228.85	-0.848	0.053	0.734	0.161	5.5
3229.71	-0.809	0.029	0.653	0.087	9.1
3230.57	-0.856	0.044	0.625	0.112	7.7
3233.15	-0.867	0.047	0.754	0.143	6.2
3234.01	-0.802	0.054	0.564	0.186	5.5
3239.18	-0.923	0.058	1.025	0.173	6.1
3240.04	-0.813	0.058	0.686	0.170	5.7
3242.62	-0.668	0.056	0.518	0.143	5.8

Velocity (km/s)	X (mas)	Error in X	Y (mas)	Error in Y	SNR
3243.49	-0.695	0.042	0.594	0.109	8.6
3244.35	-0.707	0.039	0.613	0.091	7.7
3246.07	-0.795	0.054	0.847	0.164	5.8

NOTE—Model fitting trials were run on subsets of this data. The point at (-0.226, 1.345) was omitted during all trials. Data from Wagner (private communication).

Table 4. Data for UGC 3193

Velocity (km/s)	X (mas)	Error in X	Y (mas)	Error in Y	SNR
4241.56	1.575	0.009	-1.926	0.034	21.4
4243.29	1.564	0.005	-1.921	0.024	31.8
4245.02	1.577	0.007	-1.950	0.027	28.9
4246.76	1.564	0.009	-1.950	0.034	22.7
4349.08	2.570	0.072	-4.009	0.168	6.0
4350.81	2.789	0.026	-4.624	0.072	12.0
4352.55	2.913	0.007	-4.936	0.023	33.0
4354.28	2.936	0.004	-4.889	0.015	48.6
4356.02	2.950	0.003	-4.850	0.010	69.8
4357.75	2.946	0.002	-5.034	0.009	89.5
4359.49	2.943	0.002	-5.048	0.007	102.3
4361.22	2.947	0.002	-4.970	0.007	102.0
4362.96	2.945	0.002	-4.995	0.007	99.0
4364.69	2.937	0.002	-4.982	0.007	108.3
4366.43	2.243	0.021	-3.033	0.068	9.4
4366.43	2.931	0.002	-4.977	0.007	98.8
4368.16	2.272	0.016	-3.073	0.057	12.1
4368.16	2.926	0.003	-4.983	0.010	69.7
4369.90	2.920	0.007	-5.005	0.026	28.5
4369.90	2.320	0.013	-3.048	0.045	16.3
4371.63	2.320	0.013	-3.098	0.039	18.3
4373.37	2.329	0.012	-3.069	0.038	18.0
4375.10	2.308	0.014	-3.139	0.048	15.7
4376.84	2.282	0.012	-3.193	0.040	18.8
4378.57	2.273	0.006	-3.153	0.022	33.1
4380.31	2.258	0.008	-3.095	0.028	26.0
4382.04	2.206	0.032	-3.156	0.091	8.4
4476.67	-0.497	0.007	0.908	0.025	31.3
4478.41	-0.516	0.004	0.924	0.014	52.3
4480.14	-0.515	0.005	0.884	0.016	44.7
4481.88	-0.500	0.005	0.838	0.018	42.2
4483.62	-0.495	0.006	0.876	0.020	37.5
4485.35	-0.437	0.014	0.792	0.040	22.2
4487.09	-0.471	0.022	0.823	0.064	15.4
4488.83	-0.479	0.016	0.848	0.047	18.0
4490.56	-0.594	0.012	1.151	0.033	27.1
4492.30	-0.677	0.007	1.351	0.021	38.4
4494.04	-0.548	0.020	1.112	0.048	23.0
4495.77	-0.149	0.036	0.321	0.087	15.1
4497.51	-0.300	0.021	0.630	0.054	21.6

Velocity (km/s)	X (mas)	Error in X	Y (mas)	Error in Y	SNR
4499.24	-0.459	0.005	0.975	0.016	46.0
4500.98	-0.467	0.003	0.987	0.011	65.2
4502.72	-0.470	0.004	1.001	0.013	54.6
4504.45	-0.463	0.016	1.005	0.050	14.0
4564.07	0.751	0.045	-1.293	0.162	5.2
4565.80	0.727	0.017	-1.424	0.062	12.2
4565.80	0.799	0.013	-1.629	0.051	14.4
4569.28	0.866	0.018	-1.528	0.068	11.8
4571.01	0.839	0.018	-1.607	0.065	12.0
4572.75	0.837	0.017	-1.684	0.055	14.0
4574.49	0.876	0.023	-1.593	0.081	10.6
4576.23	0.806	0.021	-1.566	0.088	9.0
4577.96	0.773	0.024	-1.549	0.091	7.6
4579.70	0.763	0.032	-1.552	0.115	5.5

NOTE—Model fitting trials were run on subsets of this data. Data from Wagner (private communication).

B. SAMPLE CONTROL FILE

The control file designates lower and upper bounds for the model fitting parameters, as well as the prior applied when fitting each parameter. It also sets various MCMC parameters, beam parameters, and important velocities related to the maser emission.

%------Lower and upper bounds for every parameter-----Lower and upper bounds for every parameter-----% U = uniform prior % N = normal (Gaussian) prior % C = "combined" prior; only applicable for D and M (this prior makes an internal transformation from D and M to M/D and M/D^2, which may speed up sampling) % % F = hold this parameter fixed (it will be held fixed at the "guess" value) % % Guess Lower bound Upper bound Prior % 60.3 57.8 62.8 F % Distance (in Mpc) 0.01 10.0 % BH mass (in 10^7 1.0 U solar masses) 4400.0 4000.0 5000.0 U % BH velocity (in km/s); note: should use the same frame + convention as the input maser velocities 1.2 0.0 3.0 U % BH x-position (in mas) -1.8 -3.0 0.0 U % BH y-position (in mas) 90.0 70.0 110.0 U % i_0 (inclination angle in degrees, with 90 being edge-on) 0.0 -100.0 100.0 F % di/dr (in degrees/mas) 0.0 -100.0 100.0 F % d^2i/dr^2 (in degrees/mas/mas) -30.0 -180.0 U % Omega_0 (position 180.0 angle in degrees) 0.0 -100.0100.0 F % dOmega/dr (in degrees/mas) 0.0 -100.0100.0 F % d^2Omega/dr^2 (in degrees/mas/mas)

% Guess	Lower Bound	Upper Bound	Prior	
0.0	0.0	360.0	F	% omega_0 (periapsis angle in degrees)
0.0	-100.0	100.0	F	% domega/dr (in degrees/mas)
0.0	-100.0	100.0	F	% d^2omega/dr^2 (in degrees/mas/mas)
0.0	0.0	1.0	F	% orbital eccentricity
1.00	0.1	10.0	F	% beam scaling parameter for position errors (unitless)
0.01	0.0	1.0	F	% x-position error floor (in mas)
0.01	0.0	1.0	F	% y-position error floor (in mas)
2.0	0.0	20.0	F	<pre>% velocity error floor for high-velocity features (in km/s)</pre>
2.0	0.0	20.0	F	<pre>% velocity error floor for systemic features (in km/s)</pre>
0.5	0.0	10.0	F	<pre>% acceleration error floor (in km/s/yr)</pre>
% 0.2	0.01	5.0	U	% redshifted feature radii (in mas)
90.0	45.0	135.0	U	% redshifted feature azimuthal angle (in degrees)
%				<u> </u>
0.2	0.01	10.0	U	% blueshifted feature radii (in mas)
-90.0	-135.0	-45.0	U	% blueshifted feature azimuthal angle (in degrees)
%				<u> </u>
2.0	0.01	10.0	U	% systemic feature radii (in mas)
0.0	-45.0	45.0	U	<pre>% systemic feature azimuthal angle (in degrees)</pre>

%						
0.0	-20.0	20.0	U	- 1 2	acceleration w for maser spot inmeasured accelerations	ts with
0/]	km/s/yr)	
% %						_0/
		ameters				
%						70
1000	%	Number of burn-in	n trials to us	e		
10000		Total number of N			ter burn-in	
1		Factor by which t				9
100		Factor by which t			•	
1		Number of simulta		-	-	
HMC	%	Choice of samples	r (HMC = Hamil	tonian N	Monte Carlo,	
		MH = Metropolis-H				
2223508	%	Set random seed t	for reproducib	oility (just use a ran	ndom
		integer)	_			
0	%	Toggle for initia	al optimizatio	on; set 1	to 1 to turn i	lt on,
		0 to turn it off				
%						
%=======						=%
		important velocit				
%=======						=%
%						
	ities should be	specified in km,	/s			
%						
4400		ty delineating th				
4470		ty delineating th	v			
0.0		sion between inpu		and CMB	frame (such t	that
	v_cmb	= v_input + cmb_o	conversion)			
%						
	-	ameters for VLBI	-			
						=%
%	0/ b# ·					
0.40		r axis of the bea				
1.60	-	r axis of the bea			at of North	
-6.7		tion angle of the	-			.
0		;le for beam scal: turn it off	ing; set to l	to turn	beam scaling	011,

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